

# CAMP-BDI: A Pre-emptive Approach for Plan Execution Robustness in Multiagent Systems

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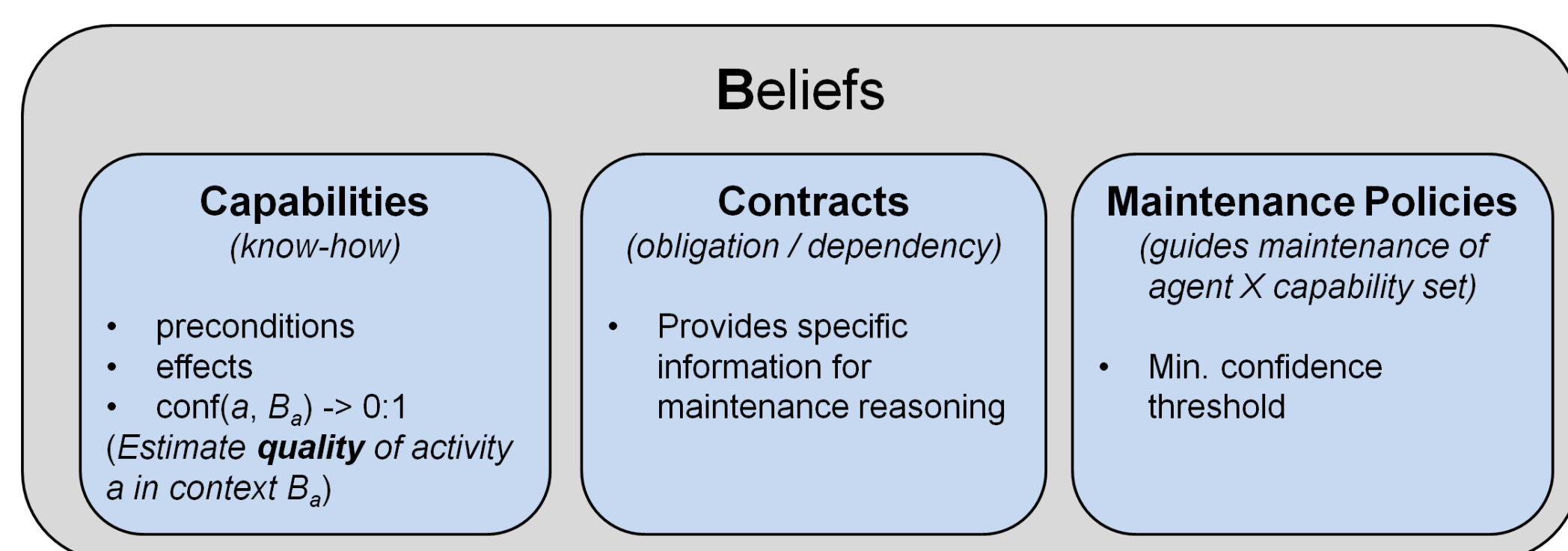
## Introduction

**Failure mitigation during plan execution** an important component in BDI agent robustness. In realistic environments exogenous change may increase likelihood of activity failure, threatening intended plans and associated goals. **Failure itself may incur debilitating consequences or costs**, hindering typical reactive recovery and potentially threatening future goals. **We argue *proactive* failure mitigation may be beneficial in realistic environments** by preventing failure-associated debilitation.

We contribute the CAMP-BDI approach (Capability Aware, Maintaining Plans) – embodying BDI agents with know-how to **introspectively reason** about intended plans, plus algorithms to **identify threats** caused by exogenous change and pre-emptively **modify (maintain) plans in response**.

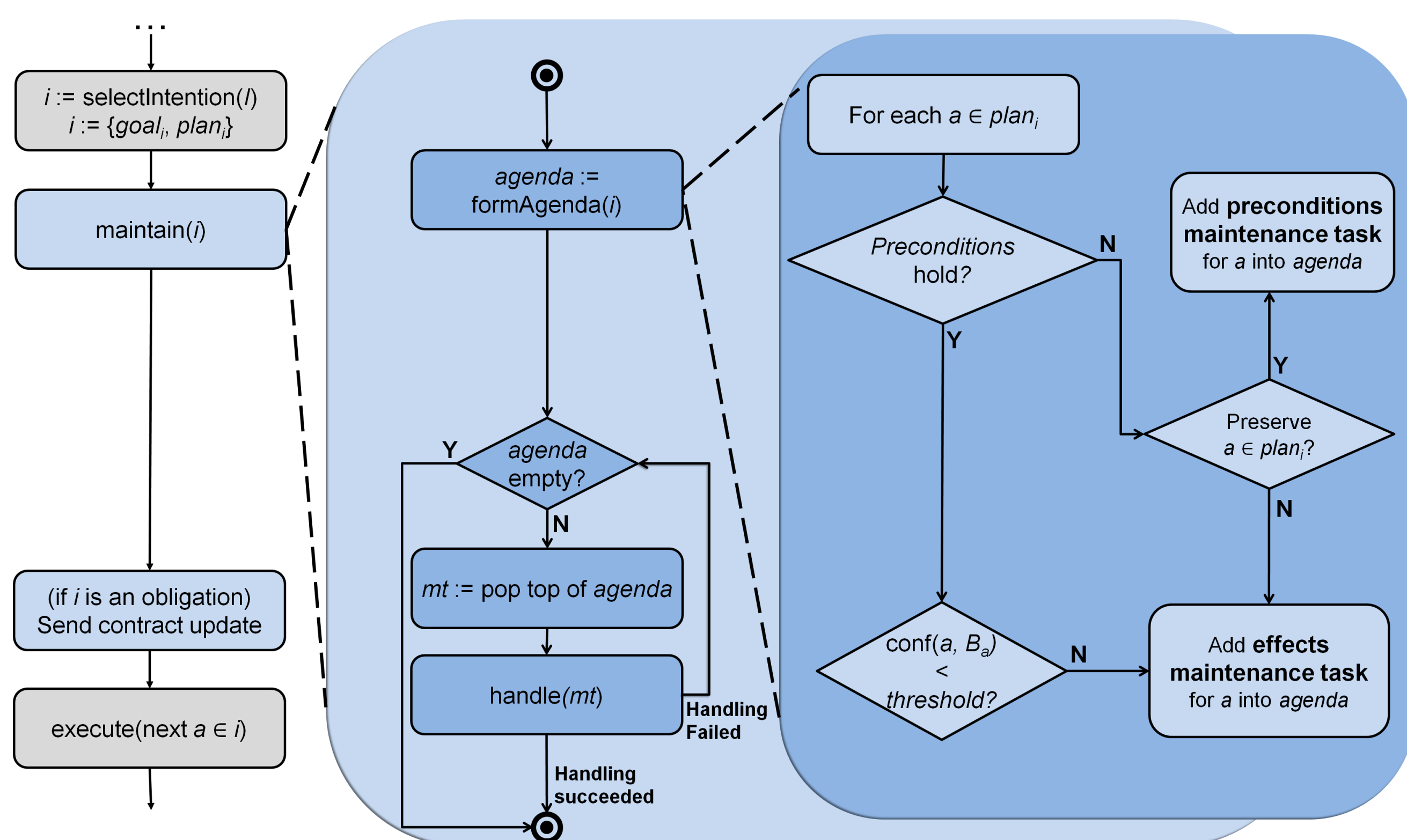
## The CAMP-BDI Supporting Architecture

CAMP-BDI agents are equipped with meta-knowledge to support maintenance, representing an extension of agent **Beliefs**;



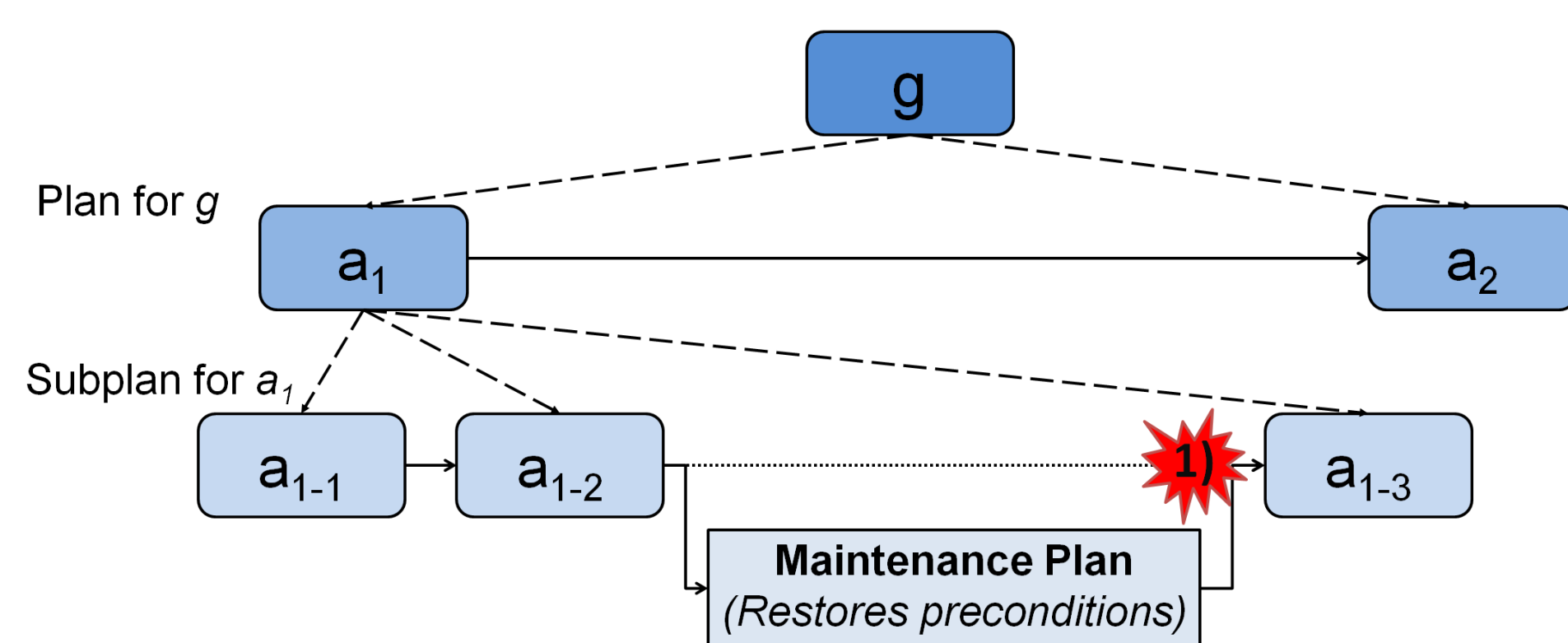
## The CAMP-BDI Reasoning Cycle

Extends BDI reasoning cycle to identify and handle threats to planned activity;



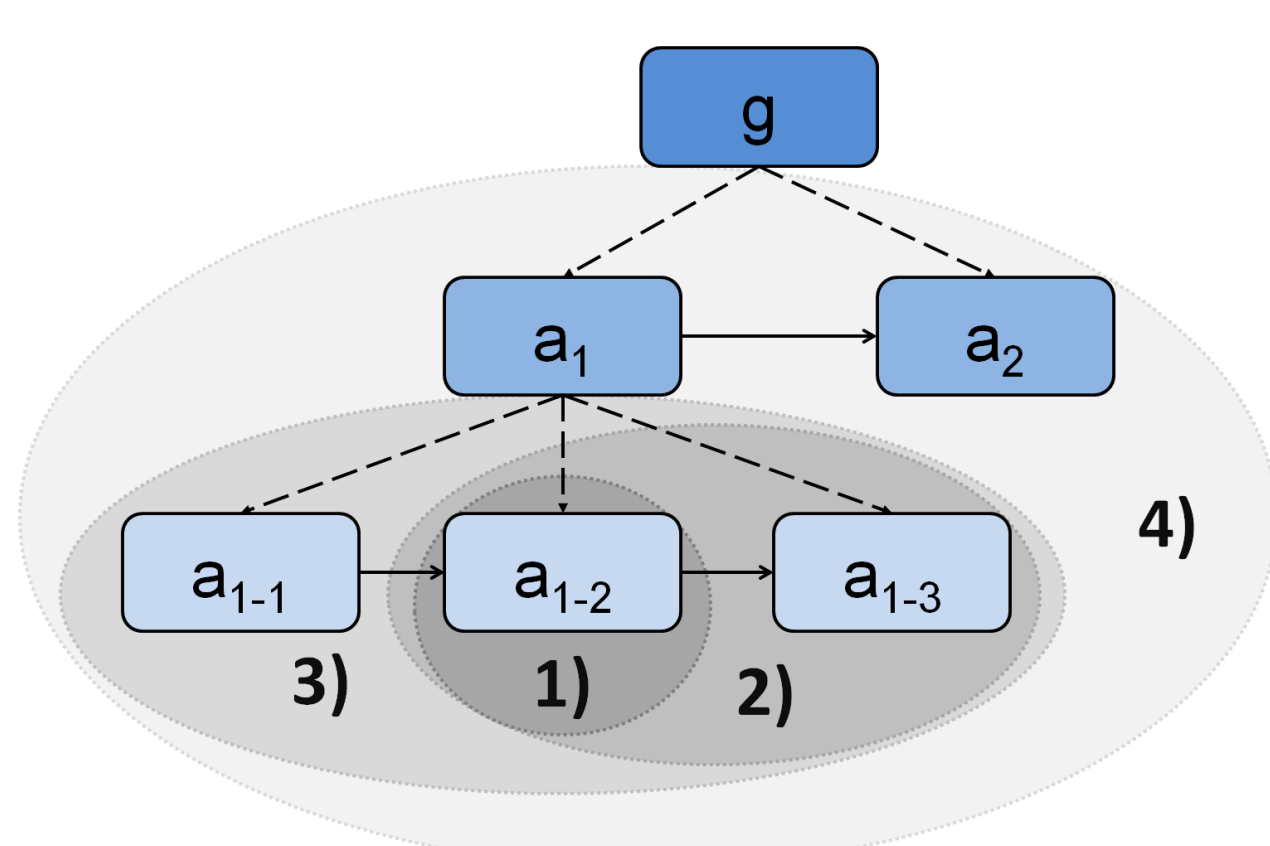
## Handling a Preconditions Task

E.g. Find and insert  $plan_M$  to re-establish  $a_{1-3}$ 's violated (1) preconditions;



## Handling an Effects Task

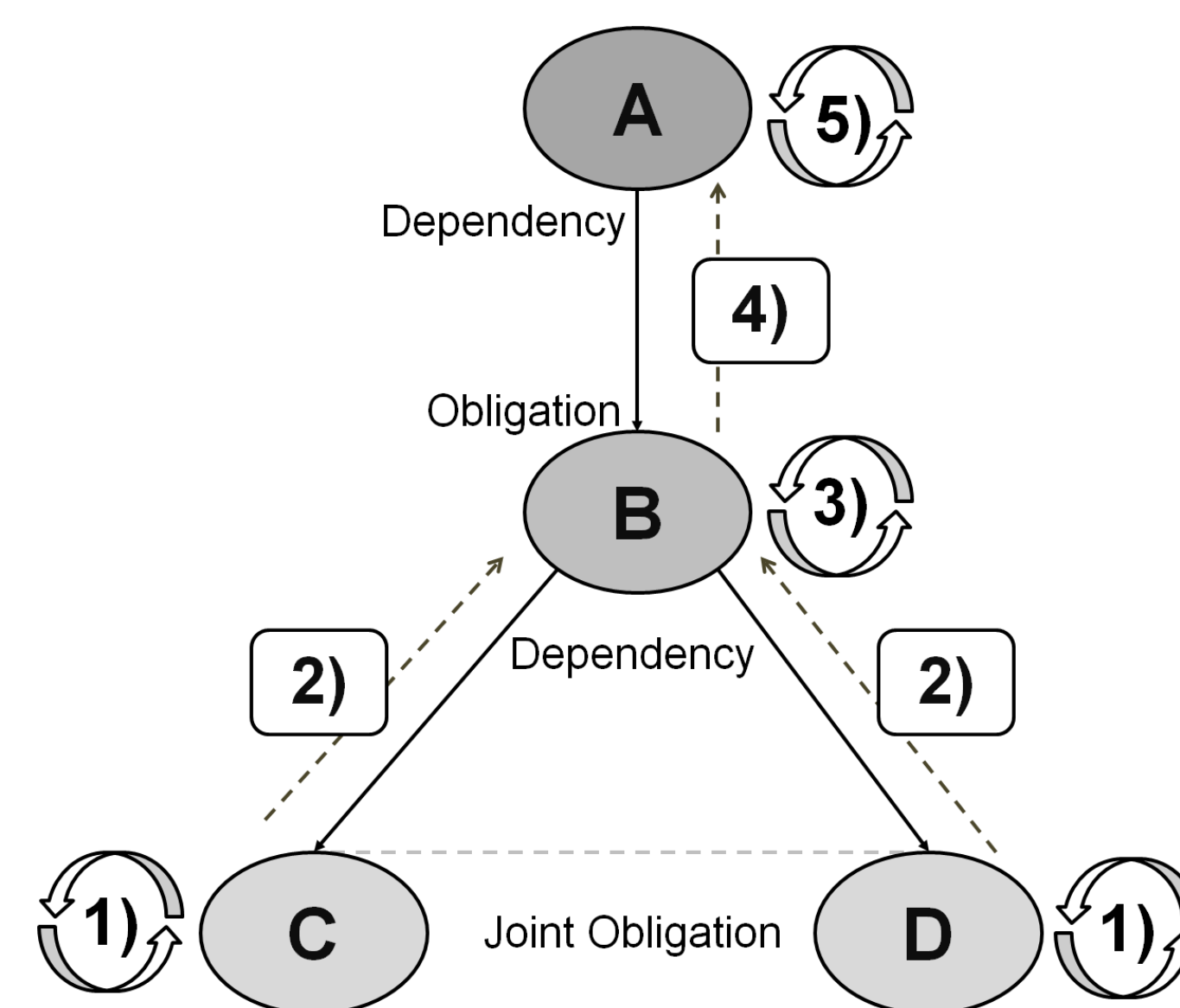
Handling a task for  $a_{1-2}$  entails **replacing some subset of the intended plan** inclusive of  $a_{1-2}$ , with a  $plan_M$  achieving equivalent effects;



- 1) Form  $plan_M$  to directly replace  $a_{1-2}$ , achieving the same effects
- 2) Insert an  $plan_M$  to replace  $a_{1-2}$  and following actions inclusive
- 3) Insert an  $plan_M$  to re-refine parent subgoal  $a_1$
- 4) Iteratively expand scope up the plan hierarchy until  $plan_M$  is inserted, or root goal  $g$  reached without success.

## Distributed Maintenance

**Decentralized** approach based upon **post-maintenance messaging** to update contract information. Dependants decide whether to **adopt responsibility** and maintain a dependant  $plan_i$  upon receipt.



- 1) Obligants C & D maintain
- 2) C, D independently send dependant B post-maintenance contract updates
- 3) B maintains the dependant intention – itself an obligation to A
- 4) B sends a post-maintenance update to A
- 5) A performs maintenance of its local dependant intention, using received information

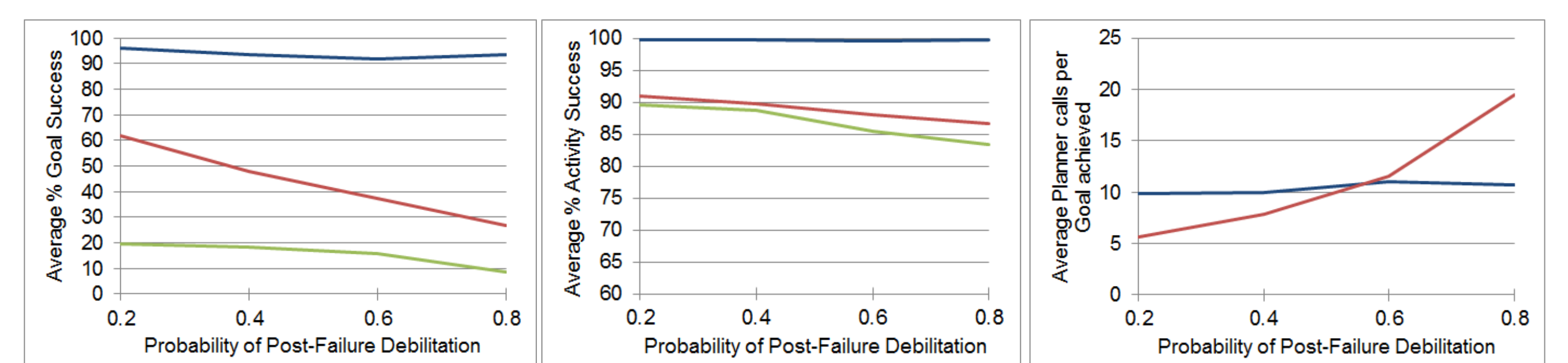
**Iterative adoption of maintenance responsibility up the dependency hierarchy** mimics local plan maintenance process across a distributed intended plan.

## Evaluation

We compared a **CAMP-BDI** multiagent system against one employing **Reactive** re-planning; a system with **No-failure mitigation** gave a worst case baseline.

A **Logistics** environment, requiring distributed plan execution by teams of heterogeneous agents, was employed for evaluation. Various **exogenous changes** could threaten activities; **landslides**, road **flooding** or **locations becoming dangerous**.

Results averaged for **10 runs** of 100 cargo deliveries, **for probabilities 0.2→0.8** of post-failure debilitation (agent or cargo damage, or cargo spillage contamination)



**CAMP-BDI shows relative consistency of performance** due to avoidance of failure consequences in the continuous environment. **Reactive approach worsens as post-failure debilitation becomes more likely**, with planning cost increasingly high as failure results in intractable recovery.

## Conclusions

- CAMP-BDI agents employ a **Proactive failure prevention** using supporting architecture knowledge and maintenance algorithms to prevent failure through plan modification.
- This offers **utility** in environments **where failure risks debilitating consequences** and capability knowledge can be used to evaluate planned future activity quality.
- We suggest CAMP-BDI offers a **complimentary approach to reactivity**, rather than a replacement – failure will always be inevitable in realistic environments.
- Further work will examine **cost**, particularly for domain analysis, use of maintenance **policies to target maintenance** behaviour, and general **optimisation**.

## Acknowledgements

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